

A Space-Based Gravitational-Wave Detector with Geometric Suppression of Spacecraft Noise (LAGRANGE)

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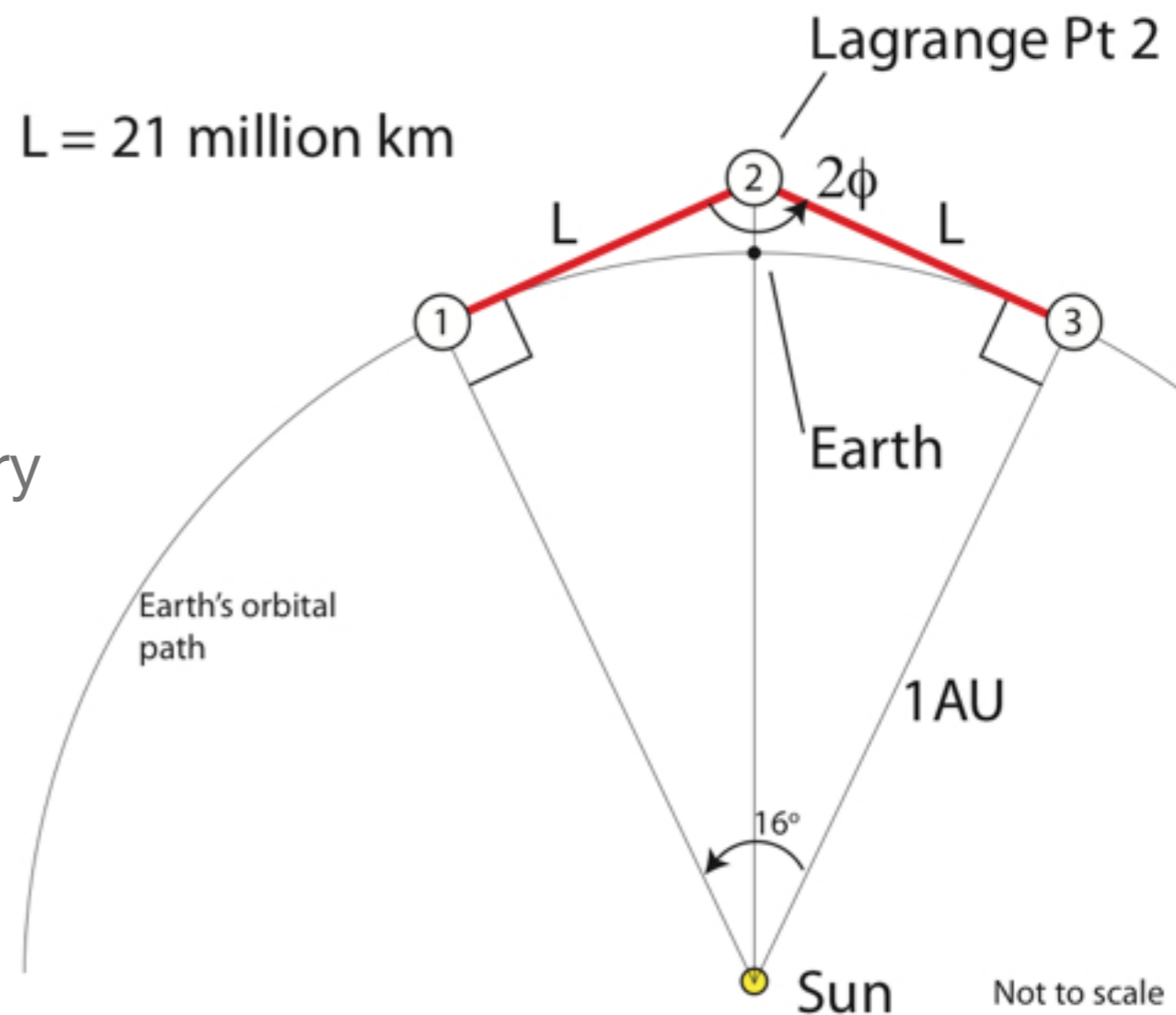
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Gravitational Wave Detector with Geometric Suppression

- Remove: high-risk technologies; that drives spacecraft requirements
- Replace Drag-free (GRS + microNewton Thrusters) with radiometer + solar wind monitor (or GOCE accelerometer)
- 3 Spacecraft with LISA-like interferometry
Separation is 4 x LISA separation
- Reduced (but interesting) science for reduced cost
- 4 rather than 6 interferometer links



Workshop Q's and A's 1.

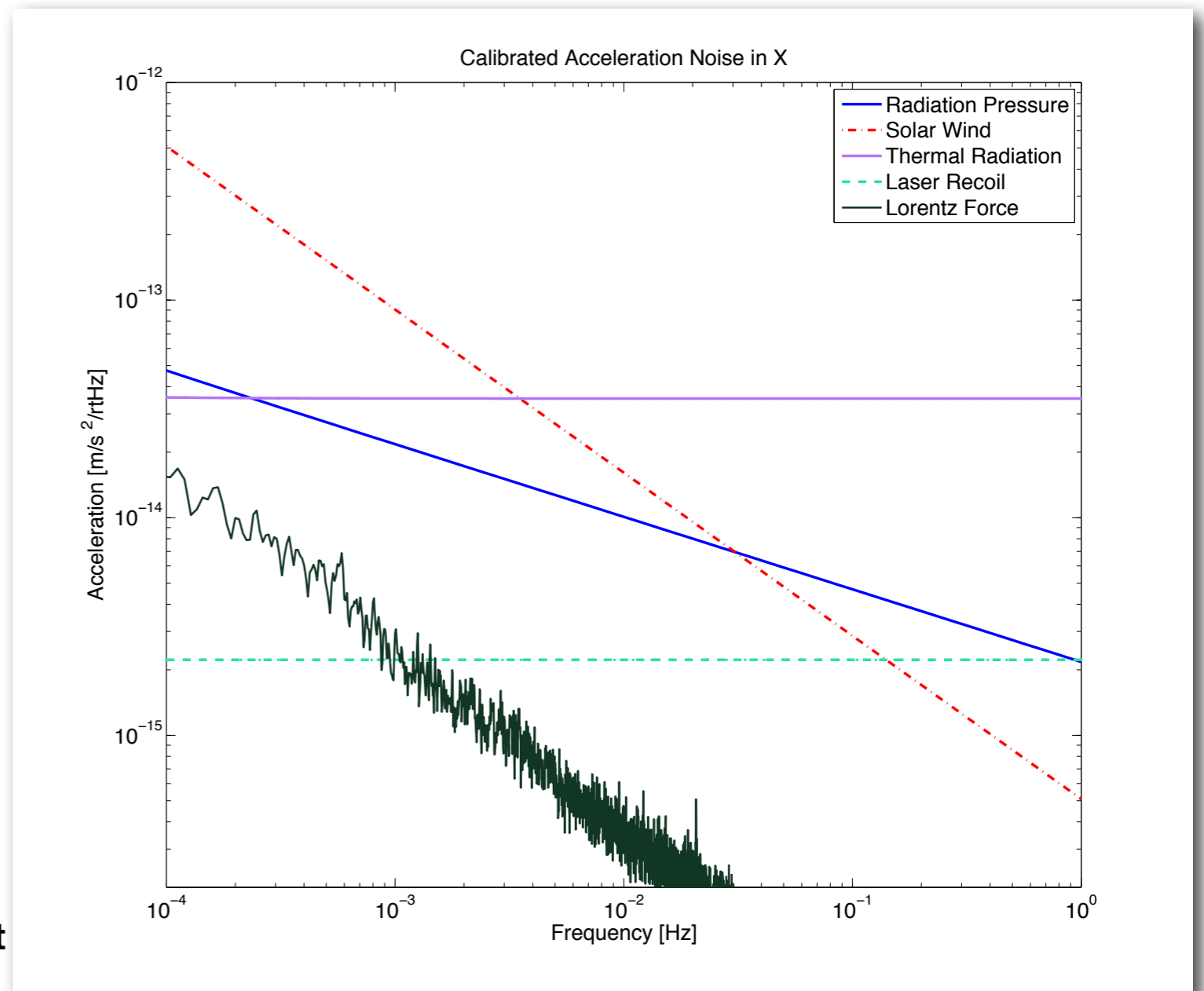
- Q: What forces are you aware of that you are not measuring?

- A: Nothing significant

Laser recoil, Lorentz force analyzed:

Also small:

- transverse orbit coupling,
- s/c dipole coupling to magnetic field gradient



Workshop Q's and A's 2.

- Q: What about internal distortions?
- A: Needs study, but expect these effects can be made small by place the beamsplitter fiducial at spacecraft center.

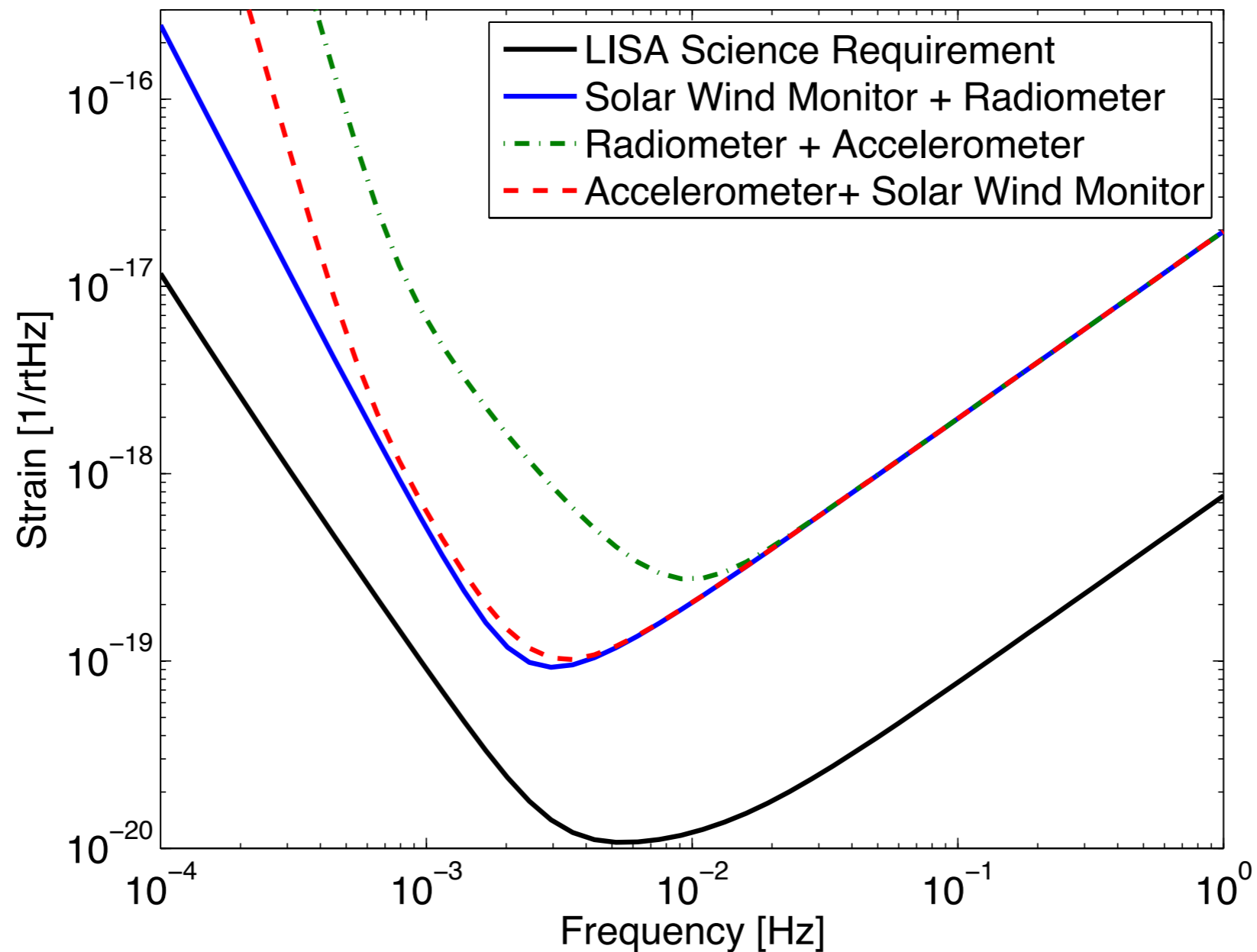
Workshop Q's and A's 3 (performance risks).

- Q: **Risk 1:** Unmodeled forces
- A: LAGRANGE s/c vs. LISA's GRS:
 - Requirements relaxed a little
 - Benefit from larger mass (though smaller mass/area)
- Q: **Risk 2:** Inaccurate models
- A: The noise couplings are simple enough that the risk seems low
- Q: **Risk 3:** Sensor failures
- A: Needs study, but the radiometer and solar wind monitors have very good reliability records.

Workshop Q's and A's 4.

- Q: Is calibration with an on-board accelerometer critical?

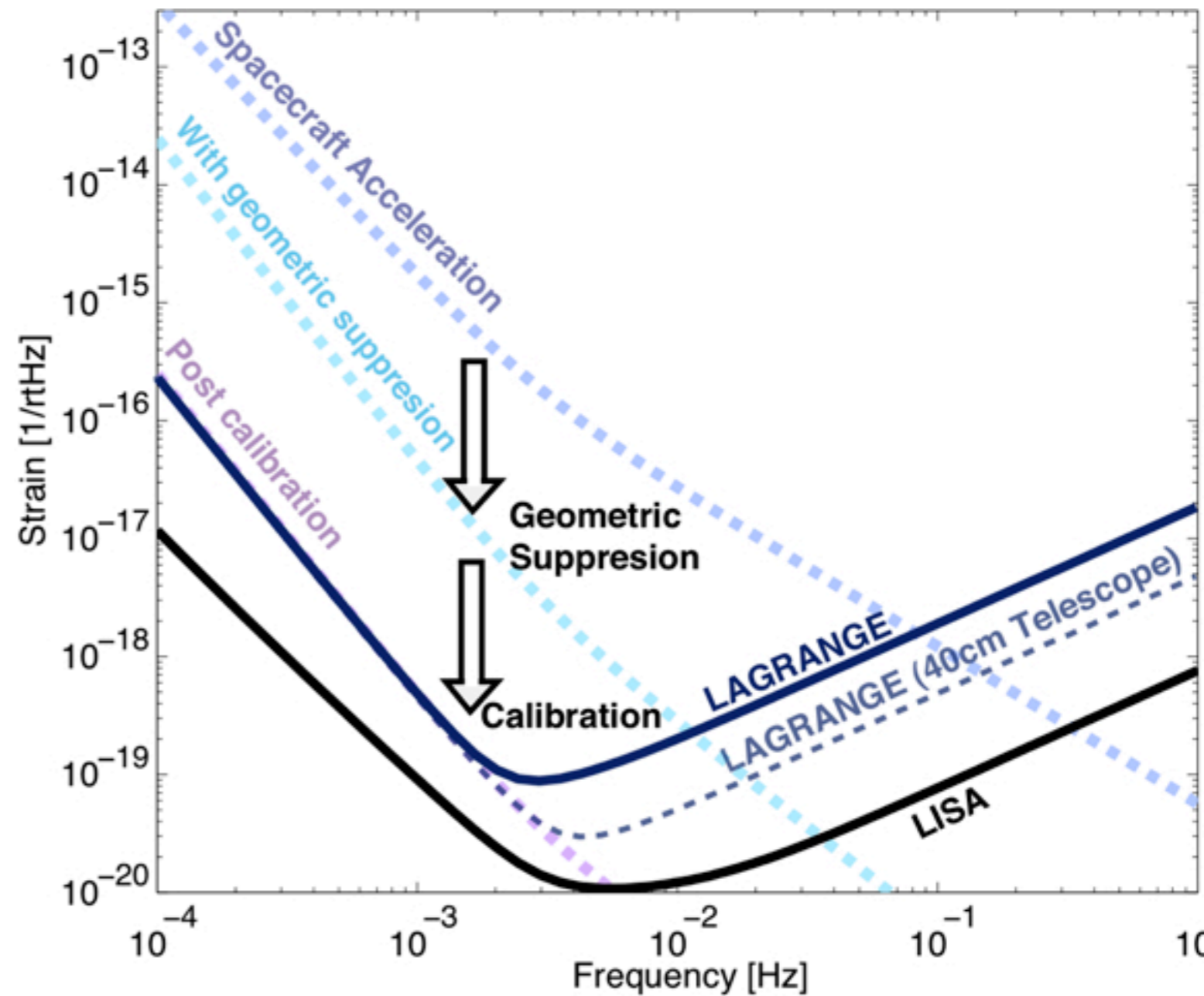
- A: No.



End of Q & A

Sensitivity

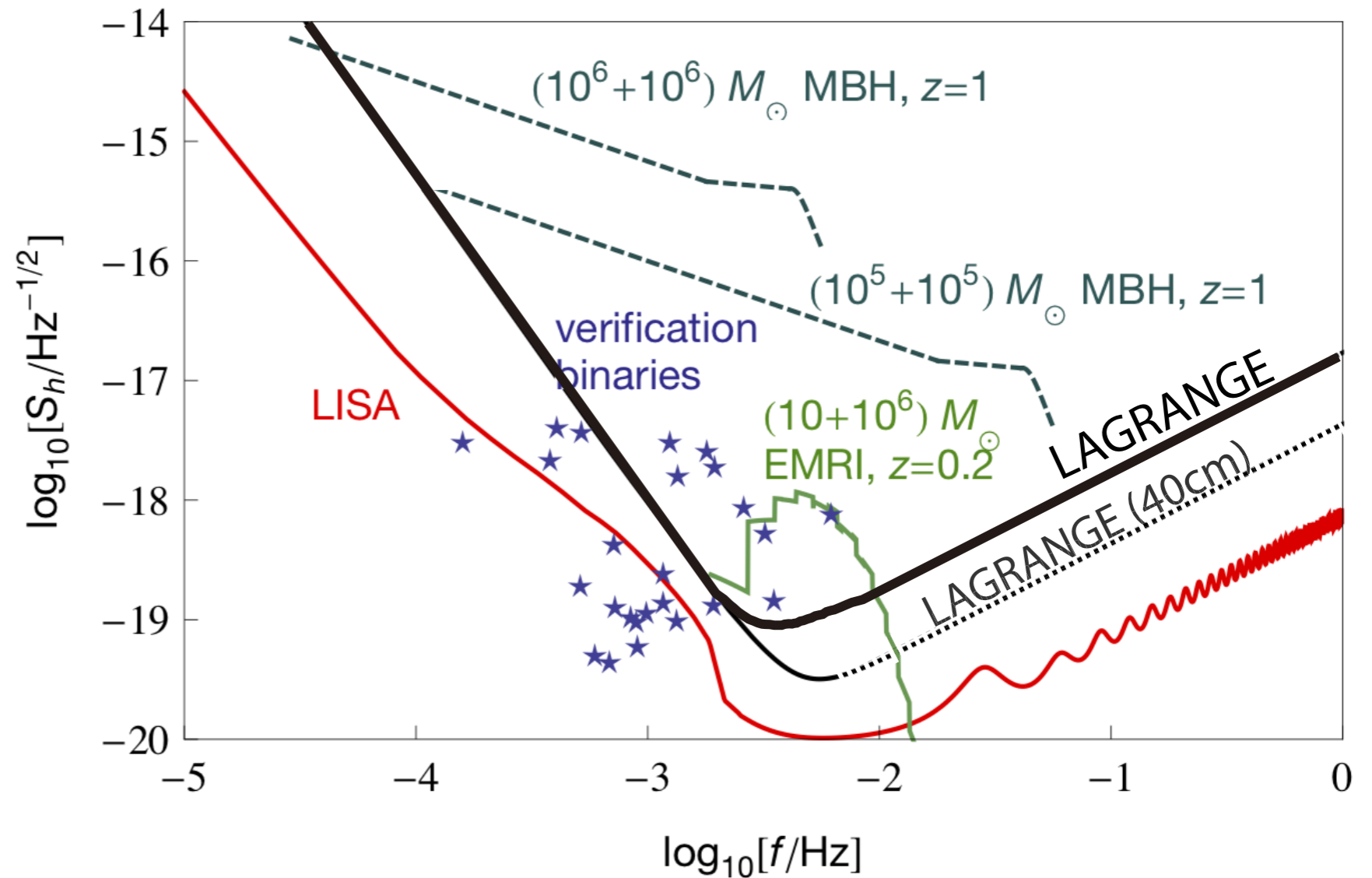
- Spacecraft noise is reduced through:
 - Geometry (factor of 100)
 - Calibration (factor of 100)
 - Low frequency limit:
Residual Solar-Wind
Acceleration



Science

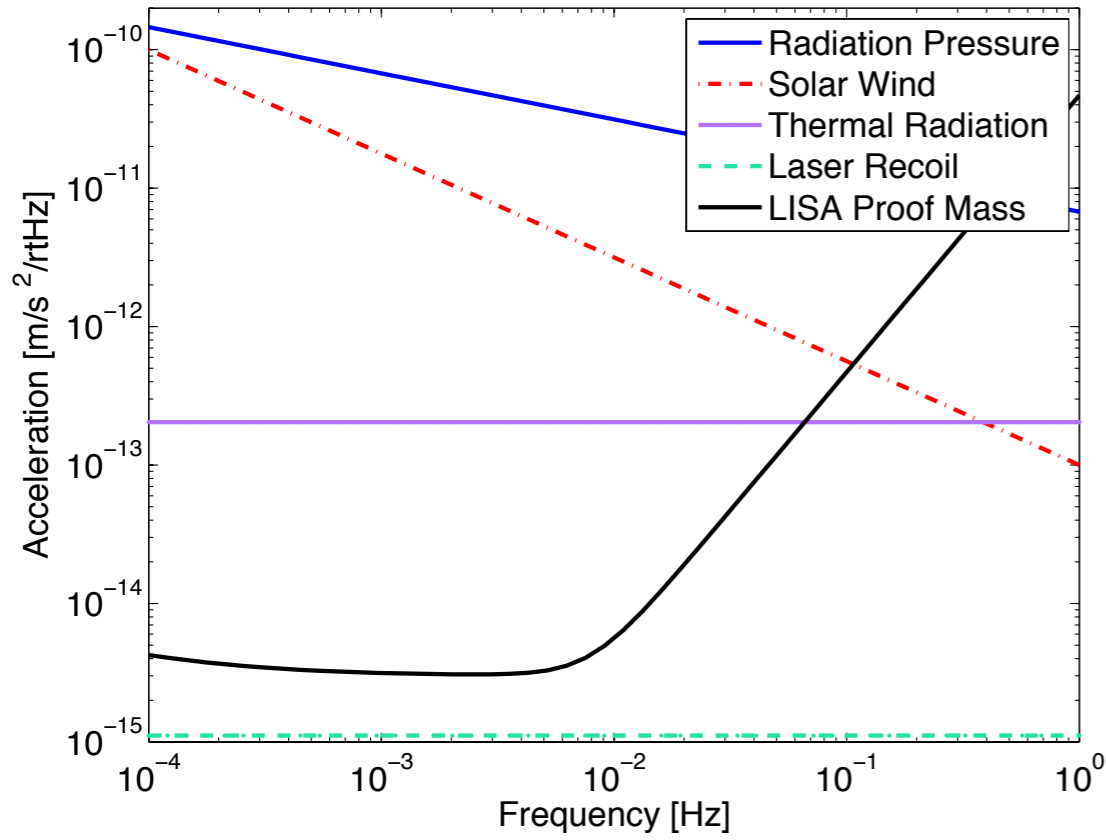
Predicted Event Rates and Event Numbers

Frequency band	100 μHz to 0.1 Hz
Massive black hole mergers	15 yr^{-1} to 25 yr^{-1} , 2-5 with SNR > 100
Extreme mass ratio inspirals	10 $M_{\odot} + 10^6 M_{\odot}$ pair seen out to $z = 0.1$
Detectable verification binaries	6, (with SNR > 5).
Galactic binaries	10000 detached binaries yr^{-1} and 1400 Am CVns yr^{-1}



Noise Budgets

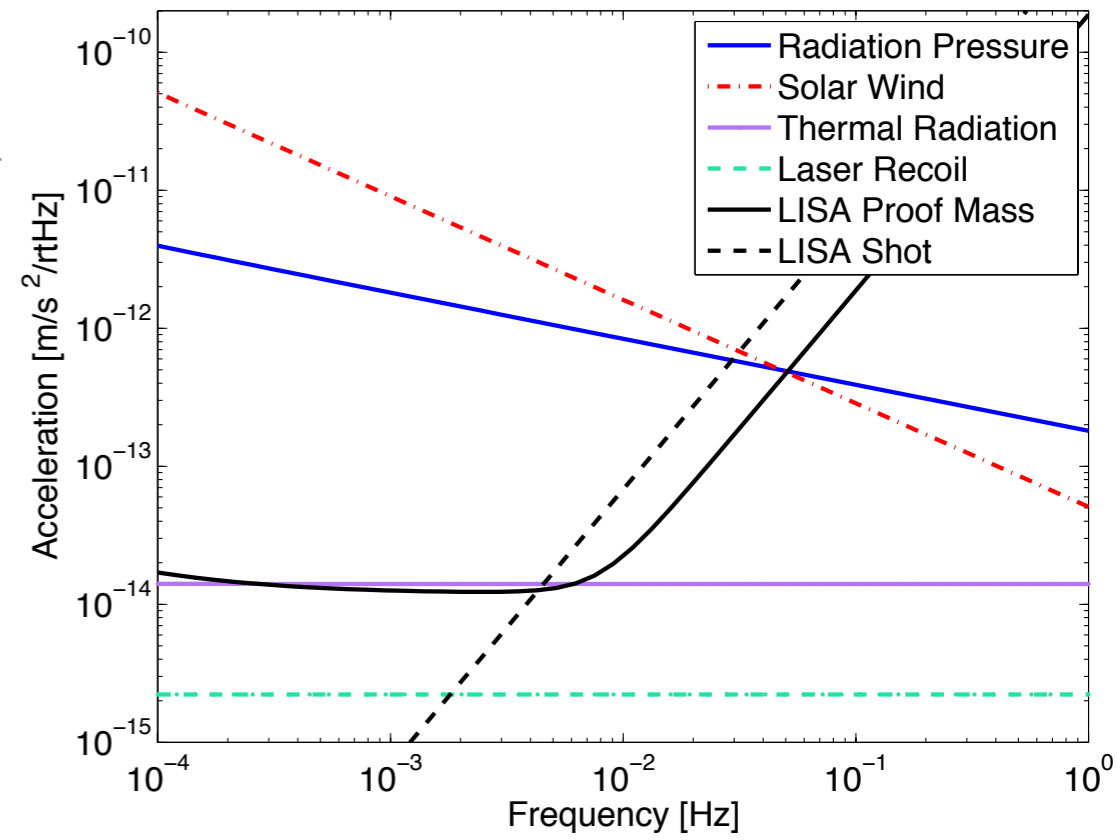
Acceleration Noise on a single spacecraft



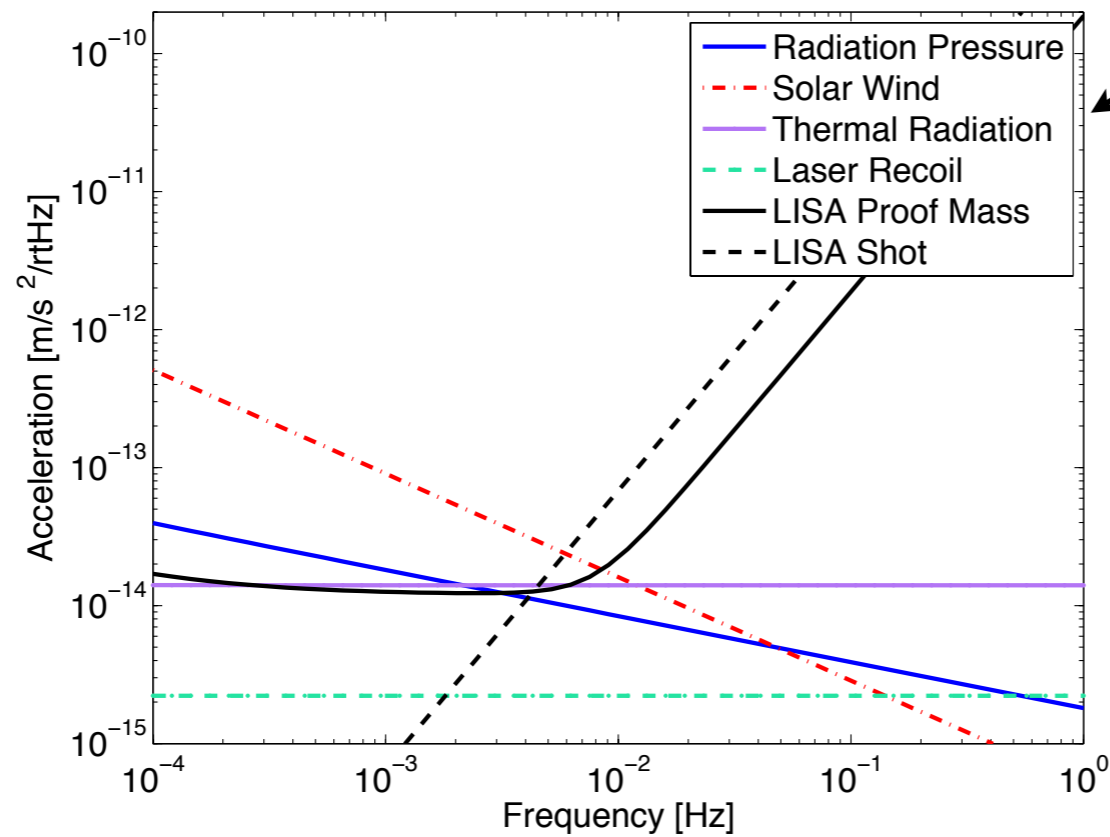
Geometric
Suppression



Acceleration Noise in X



Calibrated Acceleration Noise in X



Calibration

Instruments

- Solar wind monitor
- Radiometer
- Accelerometer

SWEPAM

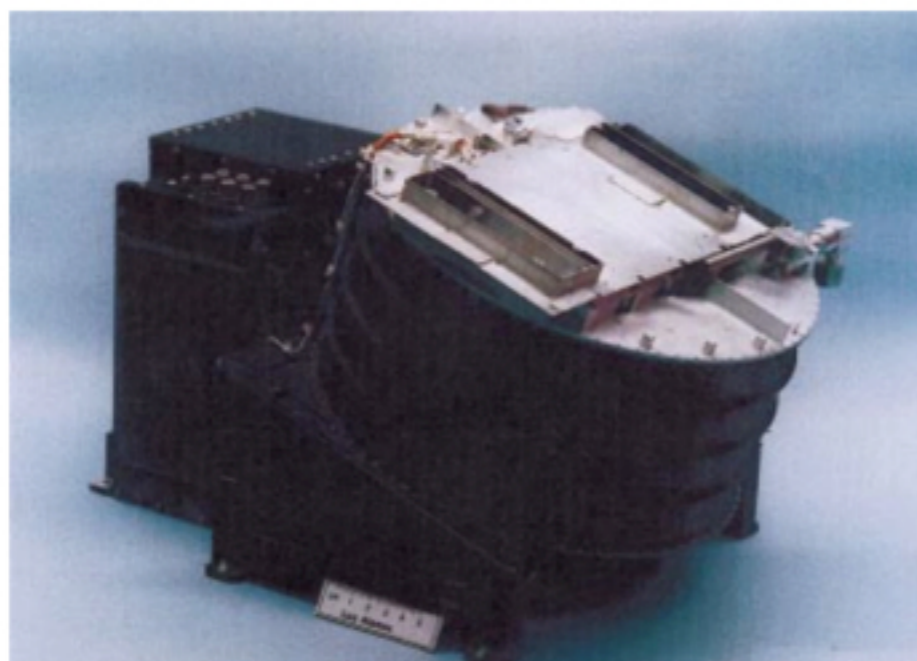


Figure 11. Photograph of the SWEPAM-I instrument. The large cylindrical housing is the sensor head; the rectangular electronics box behind it houses the high and low voltage power supplies and control electronics.

SOLAR WIND ELECTRON PROTON ALPHA MONITOR

TABLE III
SWEPAM hardware parameters

	SWEPAM-I	SWEPAM-E
Box size (L × W × H) (cm)	36 × 24 × 30	25 × 18 × 19
Mass (kg)	3.7	2.5
Power, average (W)	3.1	2.7
Power, peak (W)	3.3	2.9
Telemetry rate (b/s)	540	460
Number of CEMs	16	7
Temperature limits (°C)		
Preferred operating	0 to +20	0 to +20
In calibration	−20 to +45	−20 to +45
Operating survival	−25 to +50	−25 to +50
Non-operating survival	−30 to +60	−30 to +60
EMC interference		
DC magnetic	0.01 nT @ 10'	0.03 nT @ 10'
AC magnetic	BDL	BDL
AC electrical	BDL	BDL
Ordnance	2 dimple motors	2 dimple motors
Red tags (HV safe/arm)	2	2

BDL.: Below Detectable Levels.

McCOMAS et al, Rev Sci Inst 1998

GOCE Accelerometer

- Only one axis needed

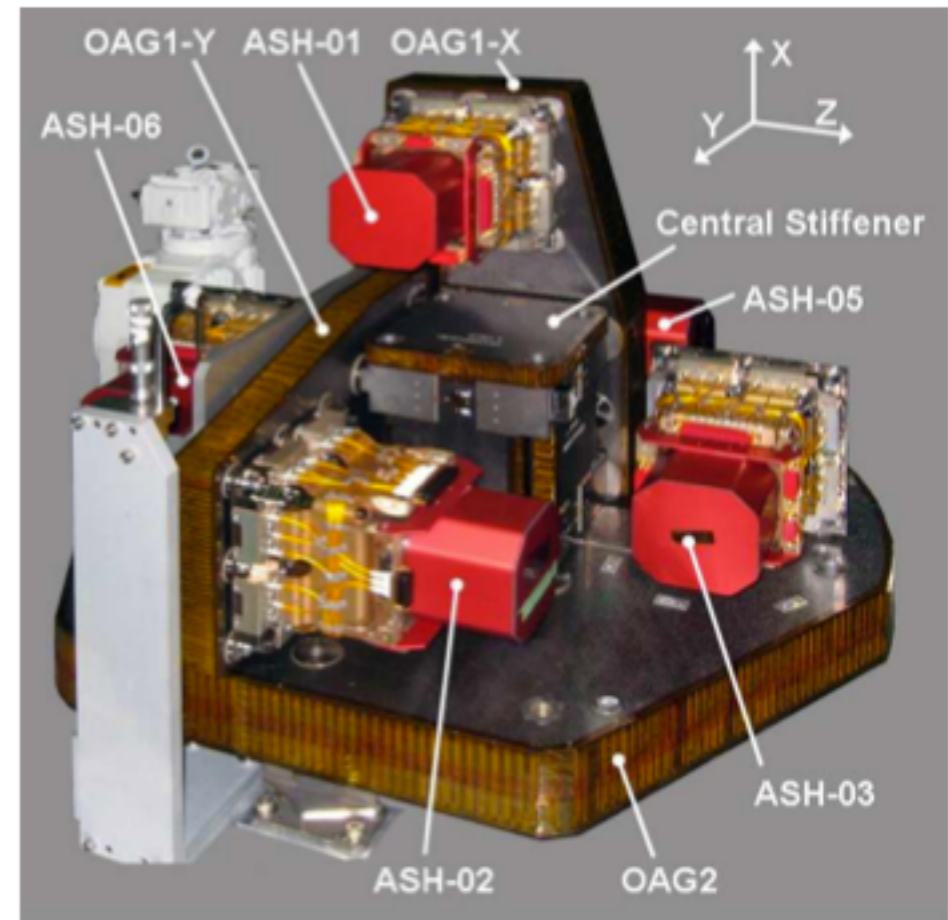
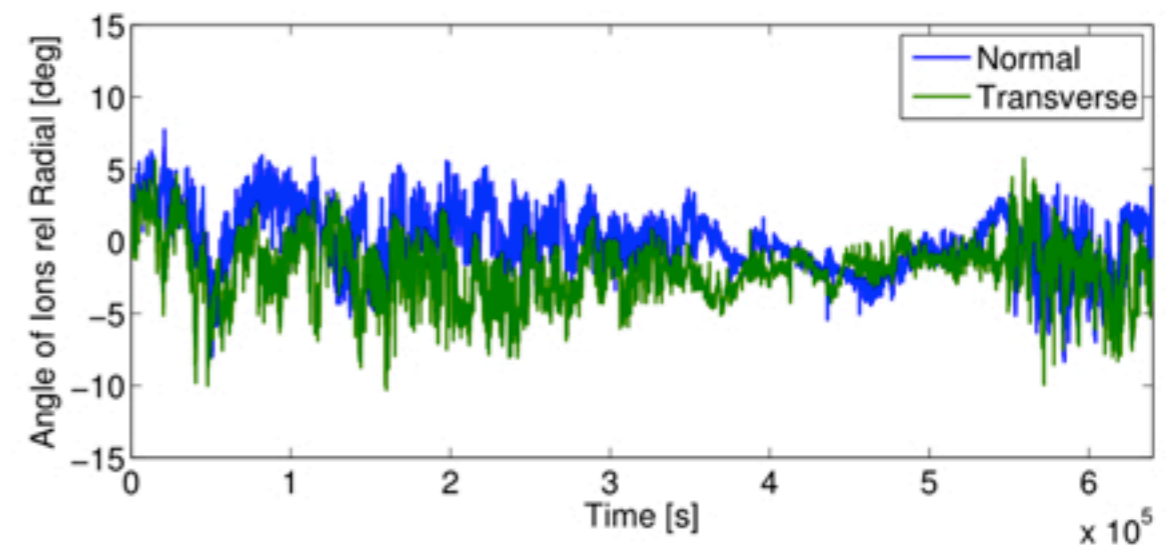
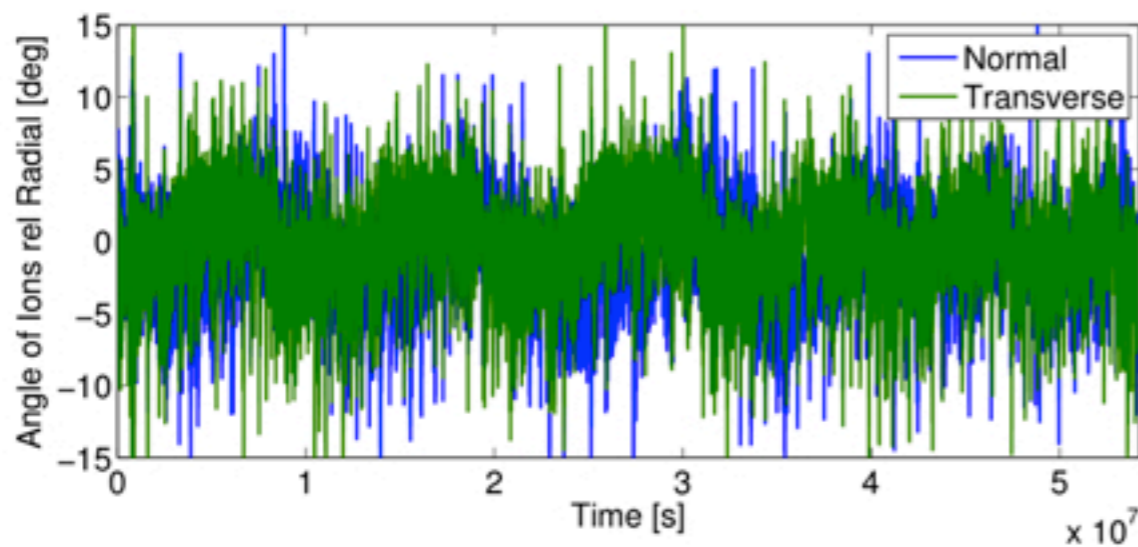
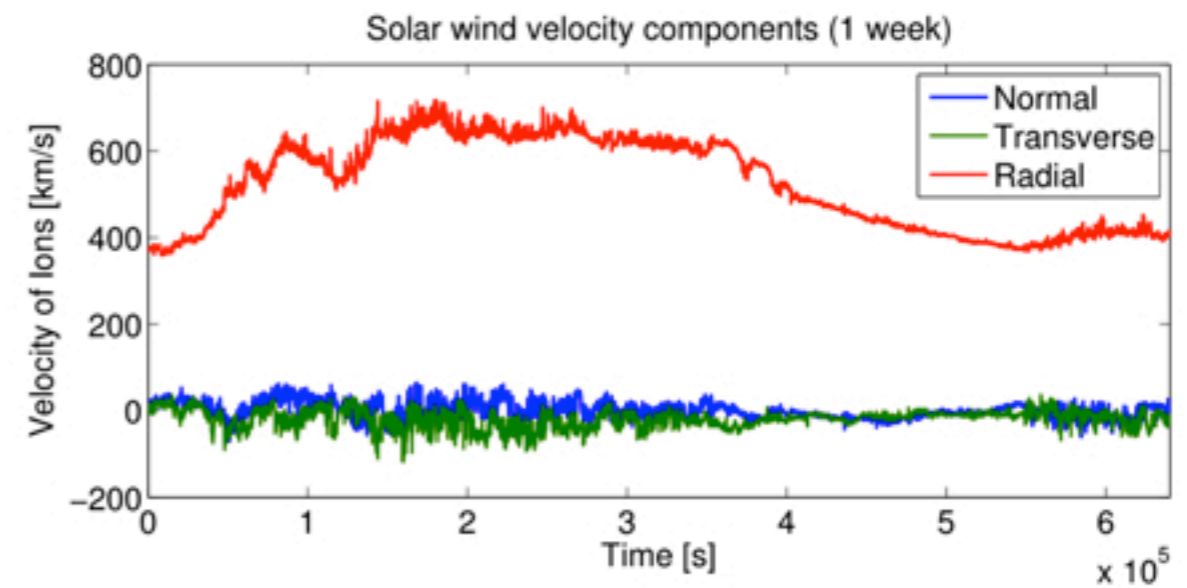
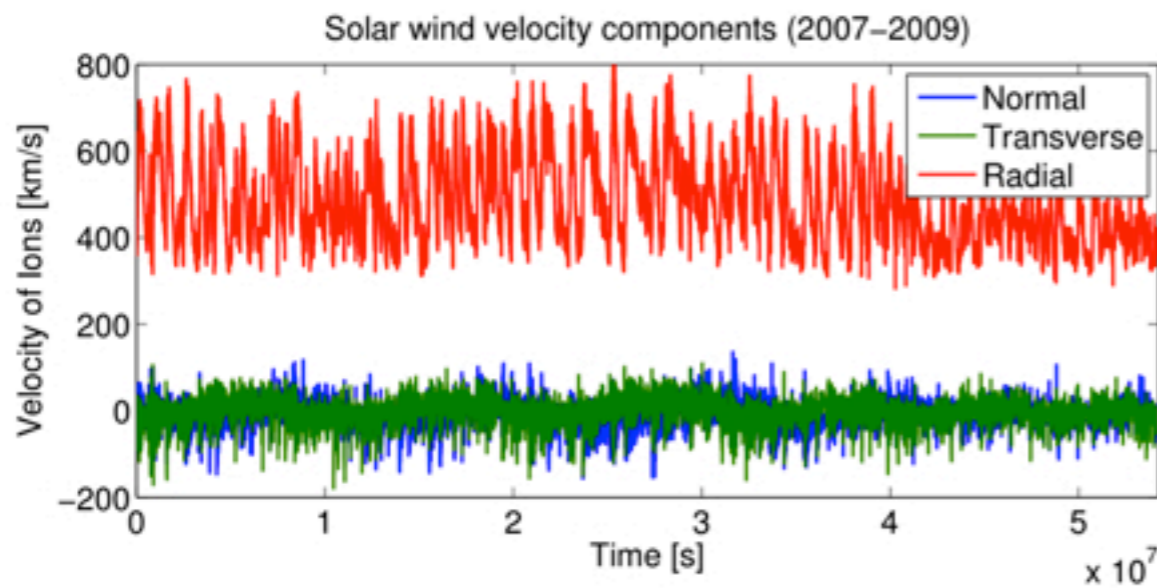


Figure 2: View of the FM Gradiometer core with accelerometer sensor heads (ASH) on the carbon-carbon structure (Photo from Thalès Alenia Space).

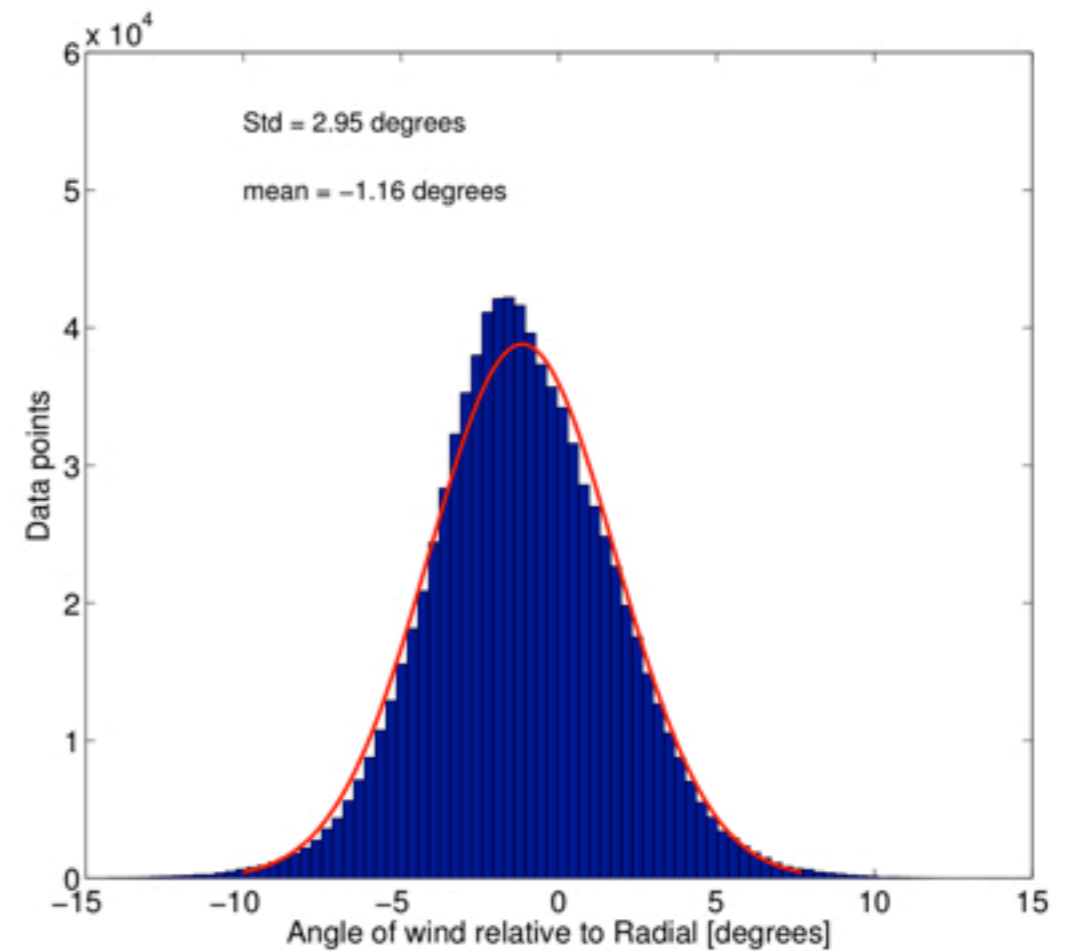
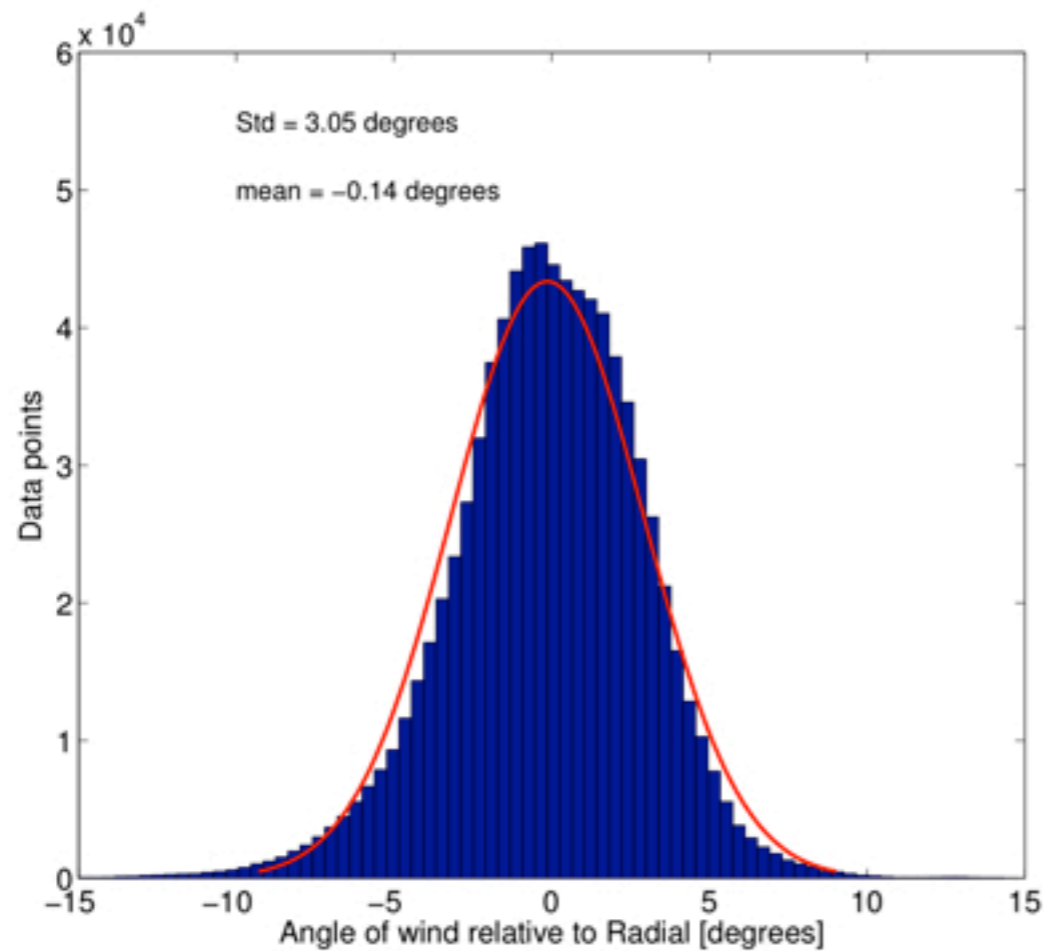
The highly variable solar wind (1)

- Variable in **magnitude** and **direction**:

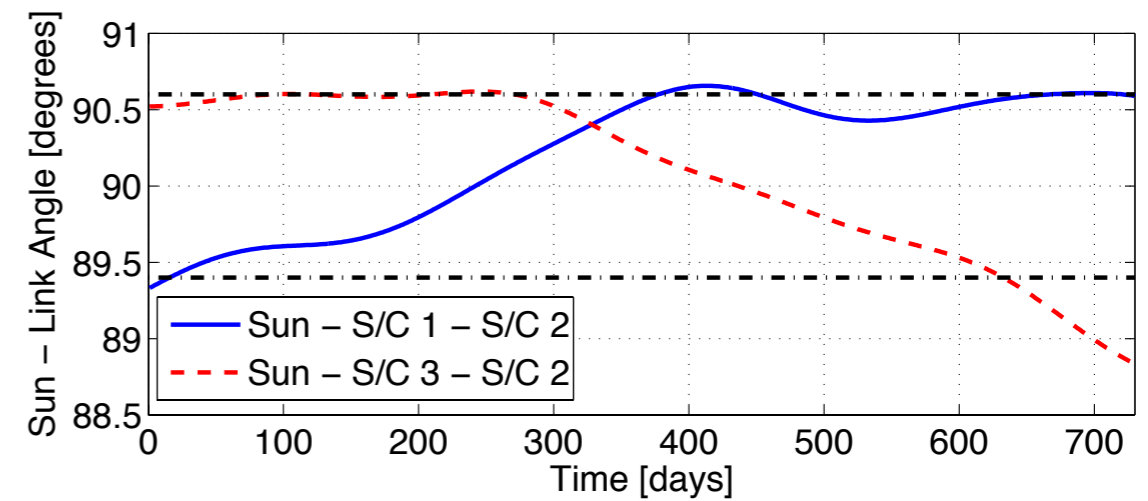
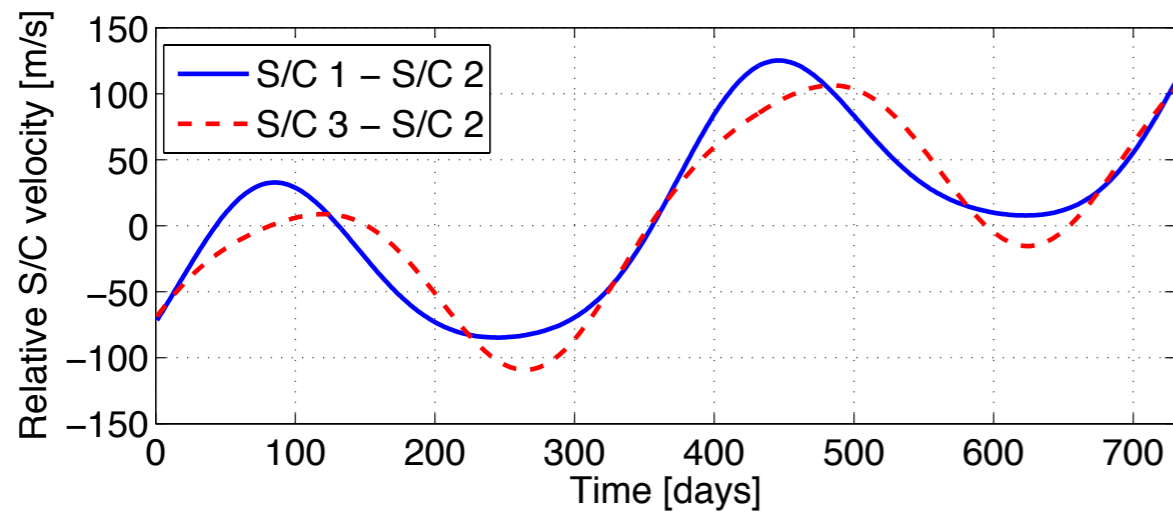
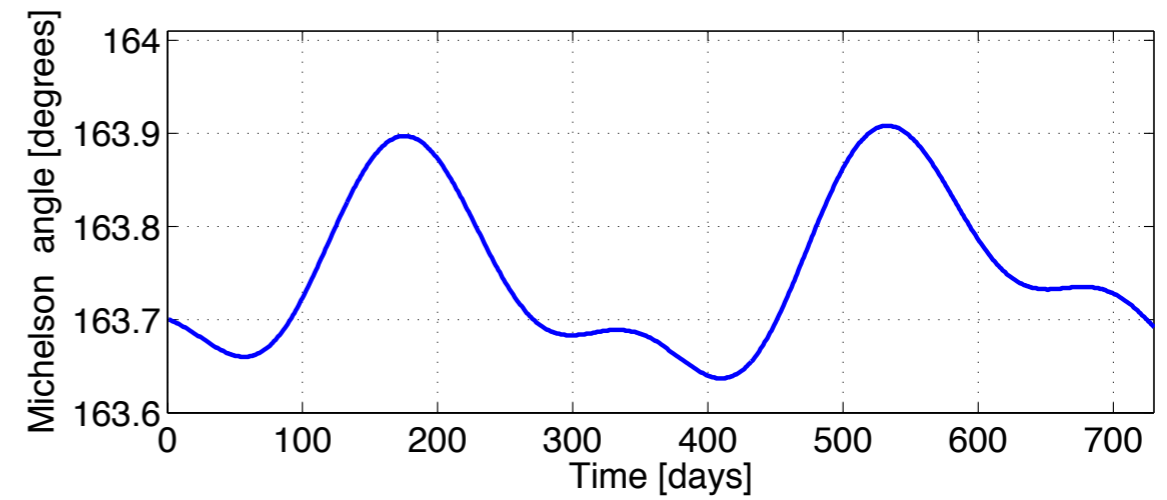
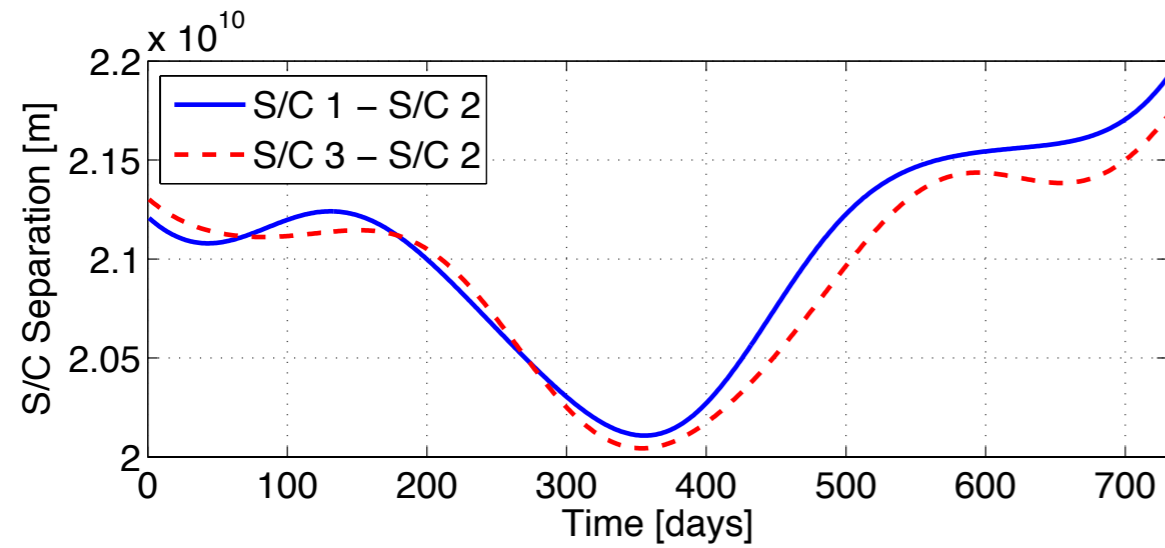


The highly variable solar wind (2)

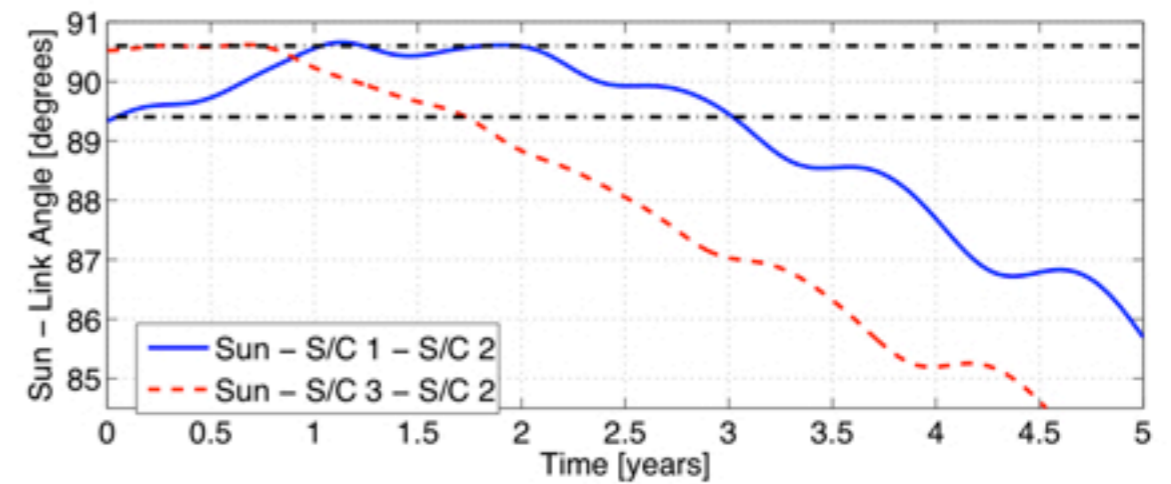
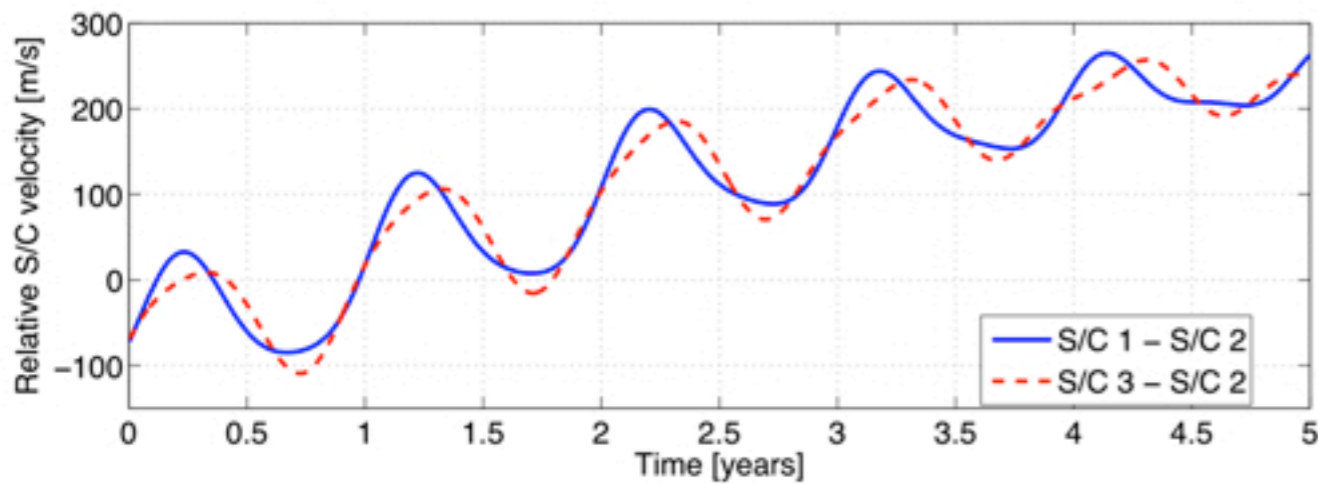
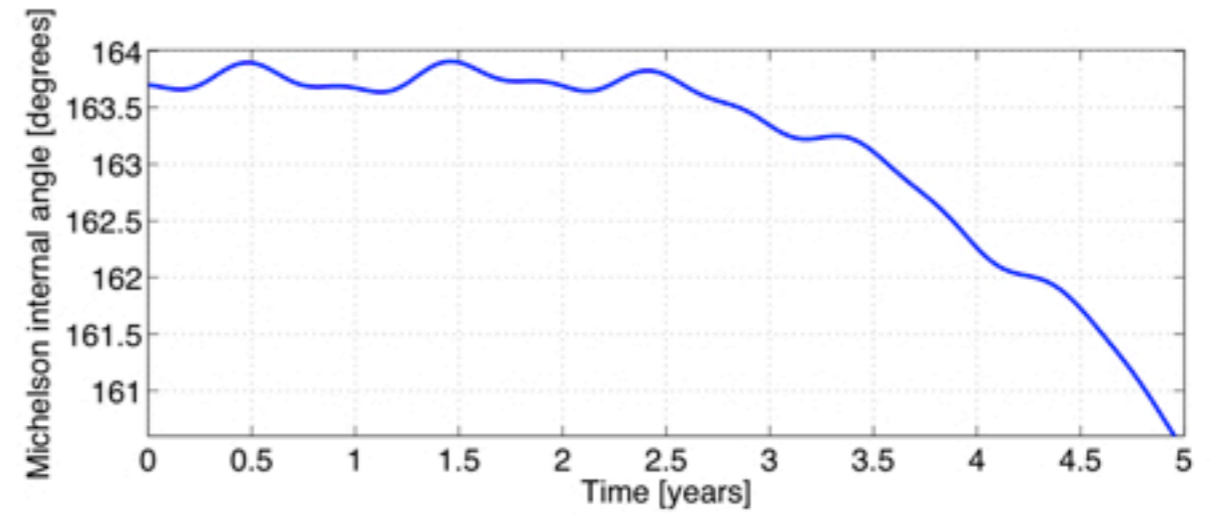
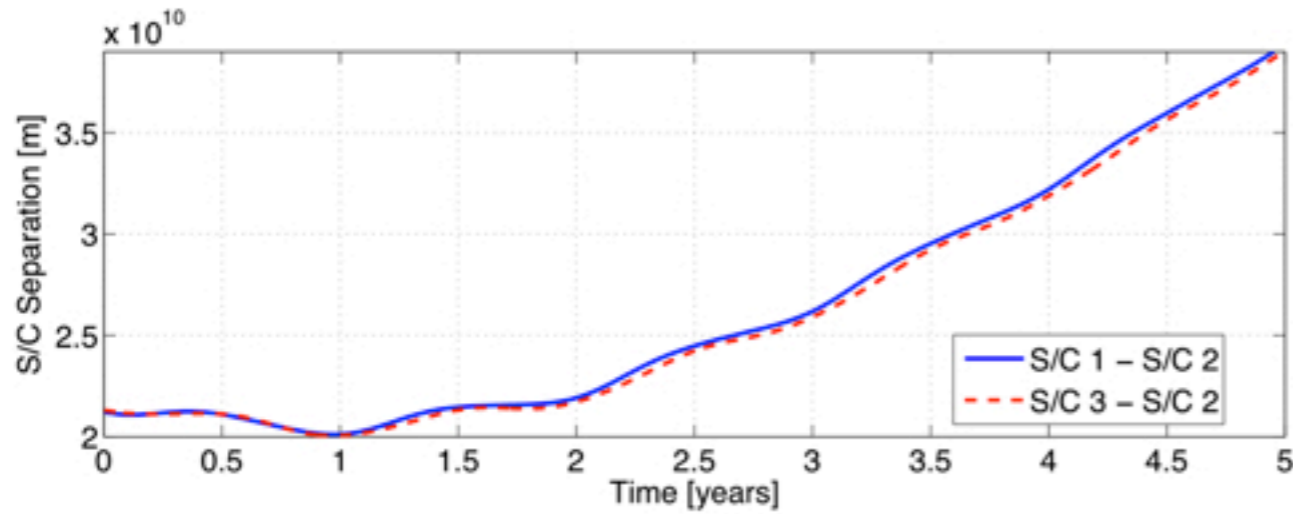
Angle of the solar wind - Histogram



Orbits, 2 year data



Orbits, 5 year data



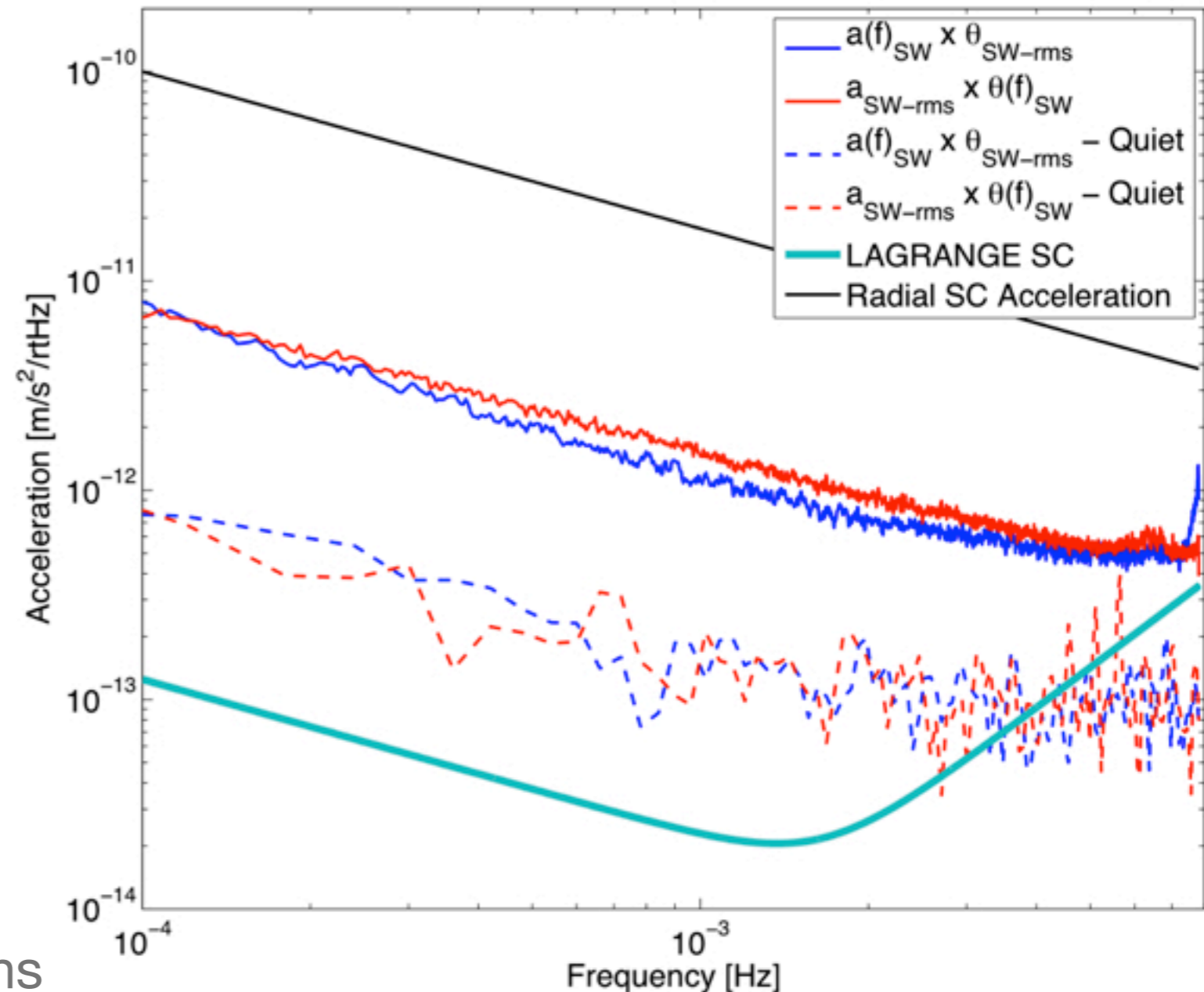
Cost Estimate

Table 4: Cost Estimate (\$M FY12)

Cost Differences between SGO-Mid and LAGRANGE	Cost (FY12\$M)
GSFC Space Gravitational Observatory - Mid (SGO-Mid)	1,400
Gravitational Reference System: \$196M cost reduction for removing six GRS units. A single GRS is estimated at \$53M using a parametric mass-based modeling tool. This estimate aligns with the SGO-Mid estimate of \$50 Million, which is used as a basis for the six-unit reduction.	(196)
Two telescope assemblies and optical benches: \$90M cost reduction. (LAGRANGE requires 4; SGO-Mid requires 6). Removal of laser pre-stabilization on each spacecraft:\$15M	(105)
Solar Wind Monitor: \$17M cost increase for three additional units. A single solar wind monitor is estimated at \$7M using a parametric mass-based modeling tool and is the basis for the two-unit increase.	17
Radiometer: \$17M cost increase for adding three units. A single radiometer is estimated at \$7M using a parametric mass-based modeling tool and is the basis for building three-units.	17
Accelerometer: \$13M cost increase for adding three units. Estimated for GRACE.	13
Attitude Control: \$40M cost savings due to a different ACS design. SGO-Mid uses Micro-Newton thrusters, whereas this mission uses reaction wheels and desaturation thrusters. An estimate of the total cost of colloidal thrusters for LISA is \$80 Million, while an estimate for the total cost of hydrazine thrusters and reaction wheels on this mission is \$40 Million.	(40)
Laser Power: \$10M cost increase due to the 1.2 Watt higher power (LISA-like) laser compared to the SGO-Mid 0.7 Watt laser.	10
LAGRANGE	1116

Solar wind - SWEPPAM instrument minimum performance

- Look for when the wind is quite - plot spectra
- This appears to occur when the wind is low velocity (~330km/s vs 800km/s max)
- This gives worse case level for SWEPPAM measurement performance, but may still be actual wind.
- This level is less than a factor of 10 from LAGRANGE assumptions



SW Noise Components

- Look at: $\Delta\rho$, Δv , $\Delta\theta$, hold other terms constant, calculate acceleration spectrum
- Density noise is largest.

